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# IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

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| In Re Application No.: | 10/083,773 | Patent No.: | 7,224,807 |
| Filing Date: | February 27, 2002 | Issue Date: | May 29, 2007 |
| Applicant: | Welsh et al. | Group Unit: | 2615 |
| Attorney Docket: | 67008-041 | Examiner: | Kurr, Jason Richard |
| For: | SYSTEM FOR COMPUTATIONALLY EFFICIENT ACTIVE CONTROL OF TONAL SOUND OR VIBRATION | | |

COMMISSIONER OF PATENTS
P.O. BOX 1450
ALEXANDRIA, VA 22313-1450

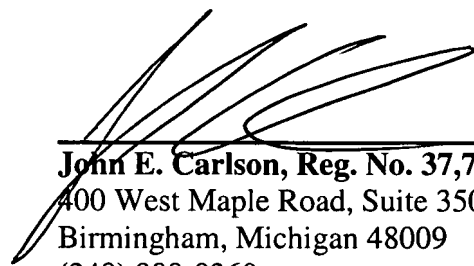## REQUEST FOR CERTIFICATE OF CORRECTION

Dear Sir:

Enclosed is a Certificate of Correction for the above-identified US Patent.

The errors are not believed to be ours and we do not believe any fee is due at this time. If any fee is due you are hereby authorized to charge Deposit Account No. 50-1482 in the name of Carlson, Gaskey & Olds. Consideration is respectfully requested.

Certificate
JUL 17 2007
of Correction

Respectfully submitted,

CARLSON, GASKEY & OLDS, P.C.

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Date: July 16, 2007

JUL 17 2007

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### CERTIFICATE OF MAILING

I hereby certify that this document is being deposited with the United States Postal Service as First Class Mail, postage prepaid, in an envelope addressed to the Commissioner of Patents, P.O. Box 1450, Alexandria, VA 22313-1450, on July 16, 2007.

Amy Spaulding

# UNITED STATES PATENT AND TRADEMARK OFFICE
## CERTIFICATE OF CORRECTION

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PATENT NO. : 7,224,807

APPLICATION NO.: 10/083,773

ISSUE DATE : May 29, 2007

INVENTOR(S) : Welsh et al.

It is certified that an error appears or errors appear in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

Claim 13 should read as follows:

The method of Claim 6, wherein said physical variable comprises a plurality of physical variables, said method further including the steps of:

f) generating a sensed signal as a function of each of said plurality of physical variables; and

g) computing harmonic estimates $z_k$ for each sensed signal $y_k$ at each sample time $t_k$ according to $z_k = z_{k-1} + \rho H(y_k - H^T z_{k-1})$, where:

$H = [\ 1\ \cos(f_d\ t_k)\ \sin(f_d\ t_k)\ \cos(f_x t_k)\ \sin(f_x t_k),\ ...]^T$ and where:

$f_d t_k$ = desired frequency;

$f_x t_k$ = frequency of unwanted information in $y_k$;

$z_k$ = estimates of harmonic content of $y_k$ at time k;

$z_{k-1}$ = estimates of harmonic content at time k-1;

$\rho$ = a variable gain that determines the corner frequency of the first order low-pass anti-aliasing filter;

$y_k$ = sensed signal vector at time k;

$(\cdot)^T$ = transpose of a vector or matrix.

MAILING ADDRESS OF SENDER (Please do not use customer number below):

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JUL 17 2007